

Imperfect Bifurcation and Catastrophy.

Introduce a New Graph!

Ex $\dot{x} = h + rx - x^3$

we add an extra parameter
This breaks the symmetry.
this looks like our symmetric pitchfork normal form.

$h \neq 0$ then h is an imperfect parameter.

We will analyze this system for both parameters
LOTS OF CASES!!

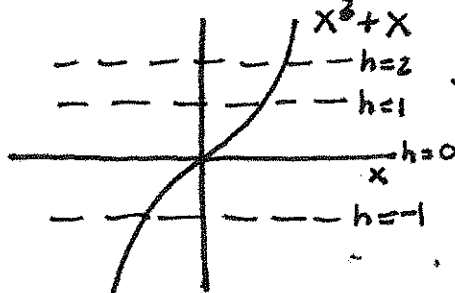
1. Solve for Fixed Points!

$h + rx - x^3 = 0$ separate:

$h = x^3 - rx$

Cases for r : $r < 0$ $r = 0$ $r > 0$

$r < 0$
let $r = -1$

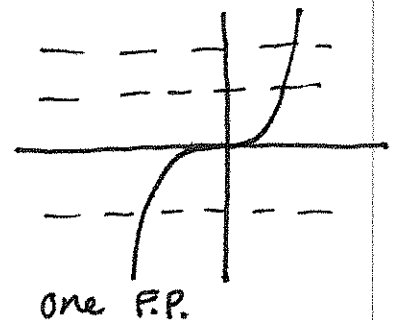


look for intersections of h and $x^3 - rx$
then $h = \text{constant}$ just a bunch of horizontal lines.

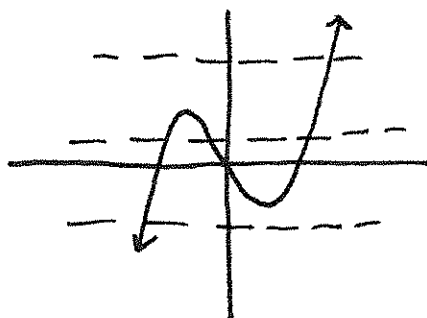
$r < 0$ always 1 FP.
as h decreases the value of the FP decreases

$r = 0$

Same as $r < 0$



$r > 0$
let $r = 1$



More complicated...
For some values of h
One FP... but some values of h have Three F.P.

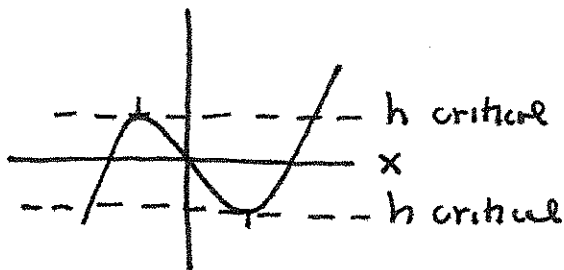
Summarize FP.

EASY — when $r \leq 0$ One F.P. For all values of h .

HARD — when $r > 0$ more complicated...

Bifurcations happen when the # of F.P. changes.

How can we solve for the "critical" h values when $r > 0$



These happen when $x^3 - rx$ reaches a local max or min.

From Calculus!
Find max and min of $x^3 - rx$

Take derivative — set to zero

$$\frac{d}{dx}[x^3 - rx] = 3x^2 - r = 0$$

$$r = 3x^2 \quad \text{or when } x = \pm\sqrt{\frac{r}{3}}$$

Plug into $h = rx + x^3$ to find critical h values.

$$h = r\left[\pm\sqrt{\frac{r}{3}}\right] - \left[\pm\sqrt{\frac{r}{3}}\right]^3$$

$$= \pm \frac{r\sqrt{r}}{\sqrt{3}} \mp \frac{r\sqrt{r}}{3\sqrt{3}} = \pm \frac{\sqrt{3}r\sqrt{r} \mp r\sqrt{r}}{3\sqrt{3}}$$

$$= \pm \frac{r\sqrt{r}[\sqrt{3} - 1]}{3\sqrt{3}} = \pm \frac{2r\sqrt{r}}{3\sqrt{3}}$$

So Bifurcation points happen at

$$h = \pm \frac{2r}{3}\sqrt{\frac{r}{3}}$$

when $r > 0$

really this is a bifurcation CURVE.

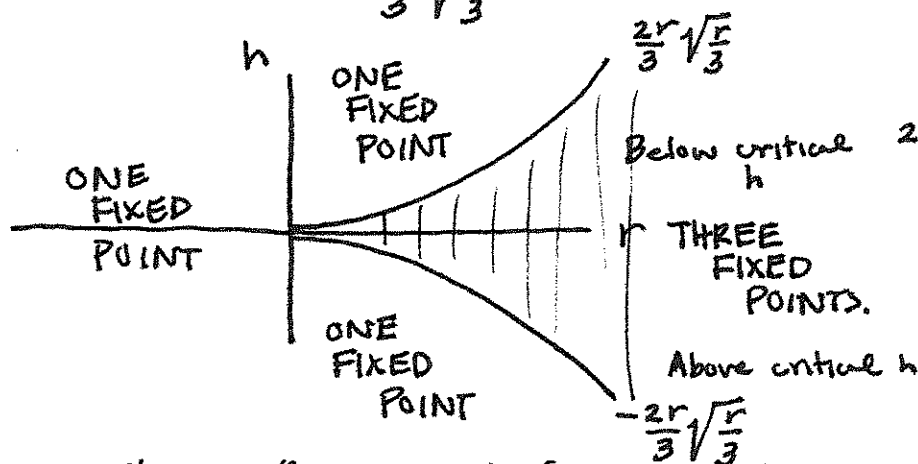
★ INTRODUCE

STABILITY DIAGRAM!

— analyze two parameters at one time.

Plot h vs r and then write in stability information!

1. draw $h = \pm \frac{2r}{3} \sqrt{\frac{r}{3}}$



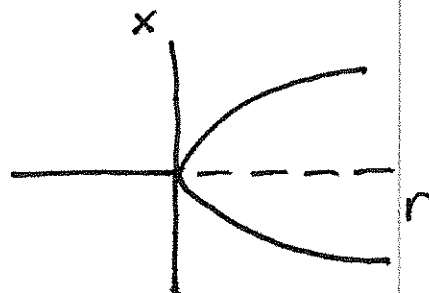
2. Write in the stability info...
How many Fixed Points.

Shows the # of fixed points as we move around parameter space!

So we know the # of Fixed Points ... what's next?

2. Stability of Fixed Points.

If $h=0$ Easy $\dot{x} = rx - x^3$
Typical Pitchfork



When $h \neq 0$ we have some cases:

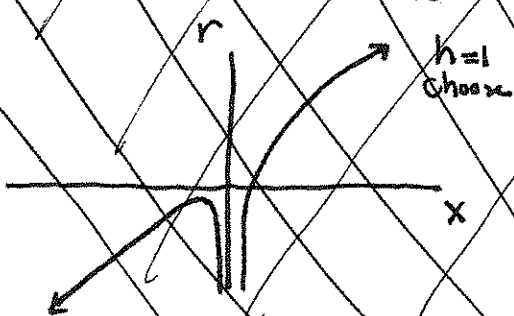
Fixed h : Plot x^* vs r

$h + rx - x^3 = 0$ solve for r

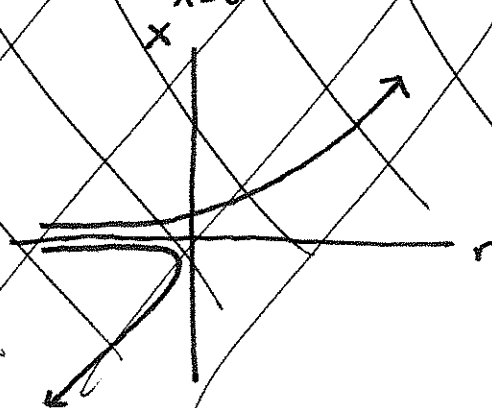
$r = \frac{x^3 - h}{x}$

asymptote at $x=0$

use the flip trick.

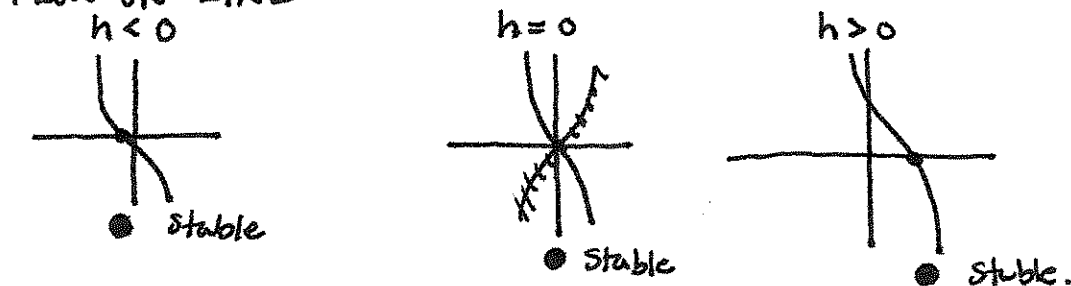


FLIP



When $h \neq 0$ we have some cases!

CASE $r < 0$ let $r = -1$
expect one FP for all h .
FLOW ON LINE



so when $r < 0$ we have one Fixed Point and it is stable.

CASE $r = 0$ still expect one FP for all h .
FLOW ON LINE
again we would find always stable.

so when $r = 0$ we have one stable Fixed Point.

CASE $r > 0$ Expect one or three FP. let $r = 1$

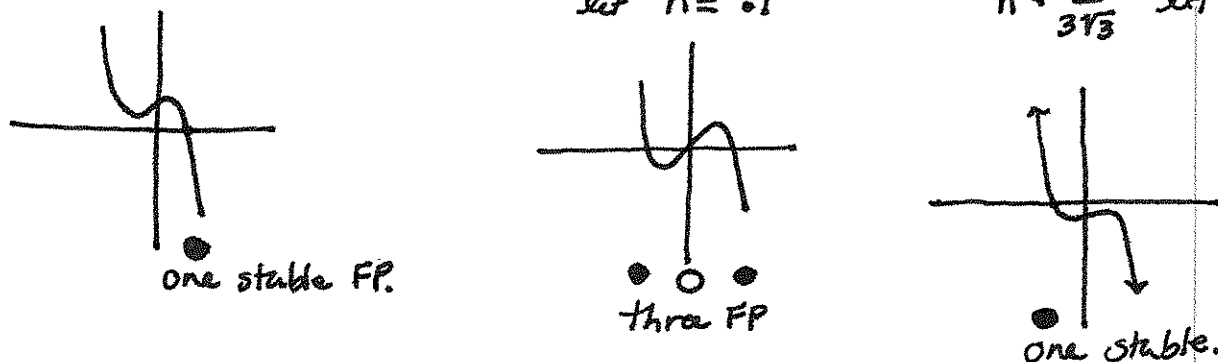
then $h = \pm \frac{2}{3\sqrt{3}} \approx \pm .3849$.

is the critical value.

$h > \frac{2}{3\sqrt{3}}$ let $h = .5$

$\frac{2}{3\sqrt{3}} > h > -\frac{2}{3\sqrt{3}}$
let $h = .1$

$h < -\frac{2}{3\sqrt{3}}$ let $h = -.5$

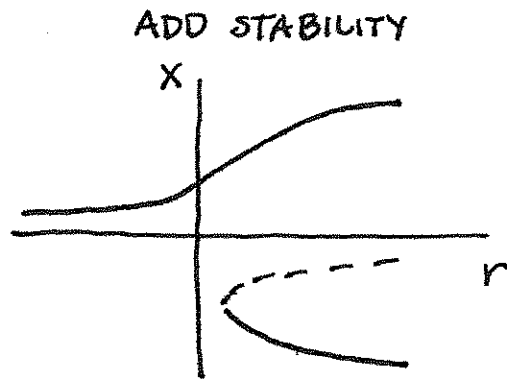
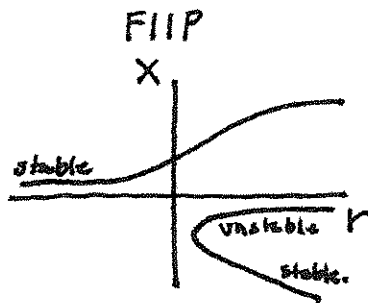
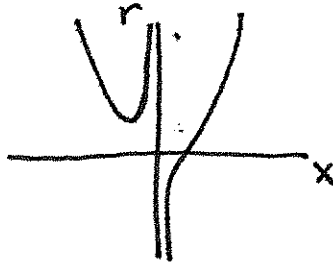


so outside of critical range one stable FP
inside Three FP The middle one is unstable.

Put this all together in Bifurcation Diagrams for ~~FLIP~~ Positive vs. Negative h .

$$h > 0$$

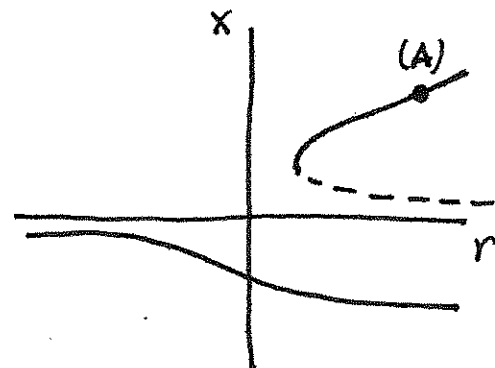
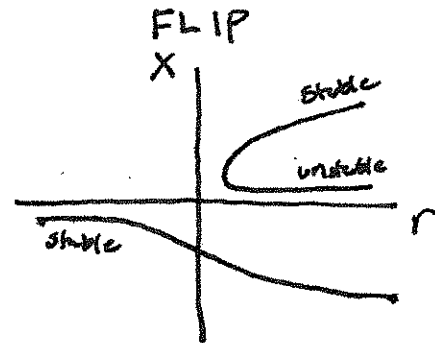
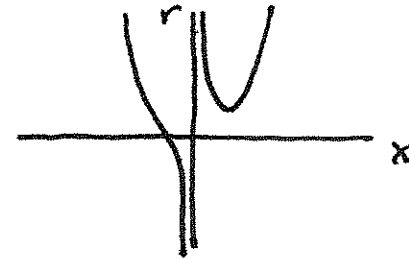
$$\text{let } h=1$$



plot
 $r = \frac{x^3 - h}{x}$
 then FLIP.

$$h < 0$$

$$\text{let } h=-1$$



In real Physical systems you can usually say $h > 0$ or $h < 0$ only — because one does not make physical sense.

CATASTROPHE.

- Instead of a smooth transition Imagine you start at (A) then slowly turn down your parameter r .
- At some point you drop off the edge to the lower solution curve and even increasing r at that point will not get you back to the top solution curve.

$$\dot{N} = RN\left(1 - \frac{N}{K}\right) - \frac{BN^2}{A^2 + N^2}$$

too many parameters to deal with individually!

NON-DIMENSIONALIZATION - a trick of applied math!

Goal - define new variables that simplify the equation.

Non-unique - there is more than one correct choice for the variables... in real life we try lots of ways and choose the best one.

1. Define the new variables...

let $x = \frac{N}{A}$ be our new dependent variable.

and $\tau = \frac{B}{A}t$ be our new independent variable.

2. Substitute new variables in one at a time.

if $x = \frac{N}{A}$ then $N = Ax$ and $\dot{N} = A\dot{x}$

our equation becomes $A\dot{x} = RAx\left(1 - \frac{Ax}{K}\right) - \frac{BA^2x^2}{A^2 + A^2x^2}$

$$A\dot{x} = RAx\left(1 - \frac{Ax}{K}\right) - \frac{Bx^2}{1+x^2}$$

good sign - things cancel.

then $\tau = \frac{B}{A}t$ and $t = \frac{A}{B}\tau$

need to substitute for $\frac{d}{dt} = \frac{d\tau}{dt} \frac{d}{d\tau}$

so $\frac{d}{dt} = \frac{B}{A} \frac{d}{d\tau}$ I can sub for $\dot{x} = \frac{dx}{dt}$ notice the $d\tau$ "cancel"

$$A \frac{B}{A} \frac{dx}{d\tau} = RAx\left(1 - \frac{Ax}{K}\right) - \frac{Bx^2}{1+x^2}$$

simplify this...

$$\frac{dx}{dt} = \frac{RA}{B} x \left(1 - \frac{Ax}{k}\right) - \frac{x^2}{1+x^2}$$

3. Define new "simpler" parameters:

$$r = \frac{RA}{B} \quad \text{and} \quad k = \frac{k}{A}$$

$$\dot{x} = rx \left(1 - \frac{x}{k}\right) - \frac{x^2}{1+x^2}$$

analyze
this equation
in terms of r and k .