

Numerical Analysis

Day 12.

Start talking about Polynomial Interpolation

GOAL - given a set of data points
find a formula (Polynomial)
whose graph passes through
those points.

When doing an experiment $\rightarrow$ TAKE DATA
what does that data look like?
 $(t_0, x_0) (t_1, x_1) (t_2, x_2) \dots$

usually we want to do something with this:

- Predict what will happen in the future t_{100}
- Fill in the gaps what happened between t_1 and t_2
- Develop a theory ... come up with an equation that matches the data.

This is also useful in making graphics more pleasing to the eye — smooth curves.

START WITH A SET OF DATA POINTS ...

these can be a wide range of functions.

given a set of functions $p_i(x)$ we look for

$$p(x) = a_0 + a_1 p_1(x) + a_2 p_2(x) + \dots + a_n p_n(x)$$

We find the coefficients $a_0, a_1, \dots, a_n$
so that $p(x)$ goes through our points.

START BY ASSUMING p_i are POLYNOMIALS.

In Mathematics — START SIMPLE and BUILD on WHAT YOU KNOW.

LINEAR INTERPOLATION - if I have only two data points to start, the best I can do is linear.
 $P_1(x) = a_0 + a_1 x$

Given two points (x_0, y_0) and (x_1, y_1) find the straight line passing through these points.

$$y_0 = mx_0 + b \longrightarrow b = y_0 - mx_0$$

$$y_1 = mx_1 + b \longleftarrow y_1 = mx_1 + y_0 - mx_0$$

solve for m

$$y_1 - y_0 = m(x_1 - x_0) \quad m = \frac{y_1 - y_0}{x_1 - x_0}$$

so $y_0 = \frac{y_1 - y_0}{x_1 - x_0} x_0 + b$ solve for b

$$b = y_0 - \frac{y_1 x_0 - y_0 x_0}{x_1 - x_0} = \frac{y_0 x_1 - y_0 x_0 - y_1 x_0 + y_0 x_0}{x_1 - x_0}$$

$$b = \frac{y_0 x_1 - y_1 x_0}{x_1 - x_0}$$

$$P_1 = \frac{y_1 - y_0}{x_1 - x_0} x + \frac{y_0 x_1 - y_1 x_0}{x_1 - x_0} = \frac{x_1 - x}{x_1 - x_0} y_0 + \frac{x - x_0}{x_1 - x_0} y_1$$

REWRITE
gather y_0, y_1

$$P_1(x) = L_0(x) y_0 + L_1(x) y_1$$

L_0, L_1 are Lagrange Basis Functions for Linear Interpolation.

Ex I have the points $(0, 0)$ and $(1, 1)$

$$P_1 = \frac{1-x}{1-0} (0) + \frac{x-0}{1-0} (1) = x$$

$P_1(x) = x$
 is the line that fits these points!
 As expected!

QUADRATIC INTERPOLATION - If we have three data points to start then we can define a second order polynomial.

$$P_2(x) = a_0 + a_1x + a_2x^2$$

given (x_0, y_0) , (x_1, y_1) and (x_2, y_2)

we write $P_2(x) = L_0(x)y_0 + L_1(x)y_1 + L_2(x)y_2$ Lagrange Formula.

where

$$\left. \begin{aligned} L_0 &= \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)} \\ L_1 &= \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} \\ L_2 &= \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)} \end{aligned} \right\} \text{Lagrange Basis Functions.}$$

A property of these basis functions:

$$L_i(x_j) = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} = \delta_{ij} \quad \text{Kronecher Delta}$$

For quadratic interpolation $L_i(x)$ are all degree 2. So $P_2(x)$ must have degree ≤ 2 .

QUESTION Are these polynomials unique?

$P_1(x)$ - straight line ... this is pretty obvious.

Lets show UNIQUENESS for the Lagrange formula for $P_2(x)$.

Assume that there is another polynomial, $Q(x)$ such that

$$\deg(Q) \leq 2 \text{ and } Q(x_i) = y_i \quad i=0,1,2$$

There is another degree 2 polynomial that perfectly fits our points.

let $R(x) = P_2(x) - Q(x)$... then

$$\deg(R(x)) \leq 2$$

$$\text{and } R(x_i) = P_2(x_i) - Q(x_i) = y_i - y_i = 0 \quad i=0,1,2$$

This means that $R(x)$ has THREE distinct roots.

BUT $\deg(R(x)) \leq 2$ can't have three roots so $R(x) = 0$.
and $P_2(x) = Q(x)$ $\square$

GENERALIZED TO HIGHER DEGREE.

Given the data points $(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)$
construct a polynomial $P_n(x)$, $\deg\{P_n\} \leq n$
such that $P_n(x_i) = y_i$ $i=0, 1, 2, \dots$

$$P_n(x) = y_0 L_0(x) + y_1 L_1(x) + \dots + y_n L_n(x)$$

where $L_i(x)$ are the Lagrange Basis Functions:

$$L_i(x) = \frac{(x-x_0) \dots (x-x_{i-1})(x-x_{i+1}) \dots (x-x_n)}{(x_i-x_0) \dots (x_i-x_{i-1})(x_i-x_{i+1}) \dots (x_i-x_n)}$$

$$i=0, 1, 2, \dots$$

$$L_i(x_k) = \delta_{i,k}$$

WRITE PSEUDO CODE ... WORKSHEET:

Read in: $(0, -1), (1, -1), (2, 7)$ $Xvals = [0, 1, 2]$
 $Yvals = [-1, -1, 7]$

Construct $L_i(x)$:

$$L_0(x) = \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)} = \frac{(x-1)(x-2)}{2}$$

Need $x=0:1:2$

values for graphing
the interpolating
polynomial

$$L_1(x) = \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} = \frac{(x-0)(x-2)}{-1}$$

For $i=1:\text{length}(x)$ PROBLEM.

$$L(i, :) = \frac{(x - Xvals(i)) \times (x - Xvals(\text{length}))}{(x_i - Xvals(i)) \times (x_i - Xvals(\text{length}))}$$

HARD TO GENERALIZE.

$$L_2(x) = \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)} = \frac{(x-0)(x-1)}{2}$$

WOULD NEED TO JUST TYPE THESE IN!

Construct $P_2(x)$:

$$P_2(x) = L_0 y_0 + L_1 y_1 + L_2 y_2$$

$$= \frac{(x-1)(x-2)}{2} [-1] + \frac{x(x-2)}{-1} [-1] + \frac{x(x-1)}{2} [7]$$

GRAPH

plot (x, P_2) .

- The Lagrange formula is good if you are doing the calculations by hand... BUT it is hard to program and generalize!!

There is another way to calculate these polynomials:

NEWTON'S DIVIDED DIFFERENCE INTERPOLATION FORMULA.

Define: The divided difference $f[x_0, x_1] = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$

- discrete form of the derivative... this is the FIRST ORDER divided difference.

Then HIGHER ORDER divided differences are defined using the lower ones.

$$f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0} \quad \text{SECOND ORDER.}$$

- similar to saying the second derivative is the derivative of the first derivative.

$$f[x_0, x_1, x_2, x_3] = \frac{f[x_1, x_2, x_3] - f[x_0, x_1, x_2]}{x_3 - x_0} \quad \text{THIRD ORDER.}$$

IN GENERAL:

$$f[x_0, x_1, \dots, x_n] = \frac{f[x_1, x_2, \dots, x_n] - f[x_0, x_1, \dots, x_{n-1}]}{x_n - x_0}$$

This is related to the derivative by the MEAN VALUE THEOREM.

$$f[x_0, x_1, \dots, x_n] = \frac{1}{n!} f^{(n)}(c)$$

NOTE: We can permute the x_i with no effect to the divided difference

$$f[x_0, x_1] = f[x_1, x_0]$$

To use this in interpolation:

Should feel similar to Taylor Polynomial.

$$P_1(x) = f(x_0) + (x-x_0)f[x_0, x_1]$$

$$P_2(x) = f(x_0) + (x-x_0)f[x_0, x_1] + (x-x_0)(x-x_1)f[x_0, x_1, x_2]$$

⋮

$$P_n(x) = f(x_0) + (x-x_0)f[x_0, x_1] + \dots + (x-x_0)(x-x_1)\dots(x-x_{n-1})f[x_0, x_1, \dots, x_n]$$

Now we can construct our polynomials term by term just by adding the next divided difference.

$$\text{Notation } D^k f(x_i) = f[x_i, x_{i+1}, \dots, x_{i+k}]$$

WRITE PSEUDO CODE ... WORKSHEET:

Read in (0,-1)(1,-1)(2,7) $Xvals = [0, 1, 2]$ $Yvals = [-1, -1, 7]$

Construct the Divided Differences. need first and second since I have THREE POINTS

~~Diff = Y values~~
~~For i = 1 to (length(Xvals)-1)~~
~~Diff[i] = (Y[i] - Y[i-1]) / (X[i] - X[i-1])~~

$$f[x_0, x_1] = \frac{f(x_1) - f(x_0)}{x_1 - x_0} = \frac{(-1) - (-1)}{1 - 0} = 0$$

SNEAKY WAY TO DO THIS!!

$$f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0} = \frac{8 - 0}{2} = 4$$

$$\text{Need } f[x_1, x_2] = \frac{f(x_2) - f(x_1)}{x_2 - x_1} = \frac{7 - (-1)}{2} = 8$$

need $x=0:1:2$
X values
to evaluate
the polynomial.

Construct the Polynomial.

$$\begin{aligned} P_2(x) &= f(x_0) + (x-x_0)f[x_0, x_1] + (x-x_0)(x-x_1)f[x_0, x_1, x_2] \\ &= -1 + (x-0)[0] + (x-0)(x-1)[4] \\ &= -1 + 4x(x-1) \end{aligned}$$

GRAPH

NEWTON

$$\begin{aligned} P_2(x) &= 4x(x-1) - 1 \\ &= 4x^2 - 4x - 1 \end{aligned}$$

LAGRANGE

$$\begin{aligned} P_2(x) &= -\frac{(x-1)(x-2)}{2} + x(x-2) + \frac{7}{2}(x-1)x \\ &= -\frac{1}{2}[x^2 - 3x + 2] + x^2 - 2x + \frac{7}{2}[x^2 - x] \\ &= \left[1 + \frac{7}{2} - \frac{1}{2}\right]x^2 + \left[\frac{7}{2} - 2 + \frac{3}{2}\right]x + [-1] \\ &= 4x^2 - 4x - 1 \quad \checkmark \quad \text{SAME} \end{aligned}$$

SNEAKY WAY TO COMPUTE: DIVIDED DIFFERENCE

Read in the Xvals and Yvals: $Xvals = [x_0, x_1, \dots]$
 $Yvals = [f(x_0), f(x_1), \dots]$

Set DIVDIFF = Yvals

$$DIVDIFF = [f(x_0), f(x_1), \dots, f(x_n)]$$

Loop forward $i = 2 : \text{length}(DIVDIFF)$
 Loop backward $j = \text{length}(DIVDIFF) : -1 : i$

Calculate the Divided Difference $DIVDIFF(j) = \frac{DIVDIFF(j) - DIVDIFF(j-1)}{Xval(j) - Xval(j-i+1)}$

end

end.

From the example: $Xvals = [0, 1, 2]$ $Yvals = [-1, -1, 7]$

$$D = [-1, -1, 7]$$

for $i = 2 : 3$

for $j = 3 : -1 : i$

$$\underline{i=2}, \underline{j=3} \quad D(3) = \frac{D(3) - D(2)}{Xval(3) - Xval(2)} = \frac{7 - (-1)}{2 - 1} = 8$$

$$\underline{j=2=i} \quad D(2) = \frac{D(2) - D(1)}{Xval(2) - Xval(1)} = \frac{-1 - (-1)}{1 - 0} = 0$$

$$D = [-1, 0, 8]$$

$$\underline{i=3}, \underline{j=3=i}$$

$$D(3) = \frac{D(3) - D(2)}{Xval(3) - Xval(1)} = \frac{8 - 0}{2 - 1} = 4$$

$$D = [-1, 0, 4]$$

Then to construct the polynomial:

$$P_2 = D(1) + (x - Xval(1))D(2) + (x - Xval(1))(x - Xval(2))D(3) \\ = -1 + (x - 0)[0] + (x - 0)(x - 1)[4] \quad \checkmark$$